

# Measurement and Modeling of Tire Forces on a Low Coefficient Surface

April 4, 2006

by:

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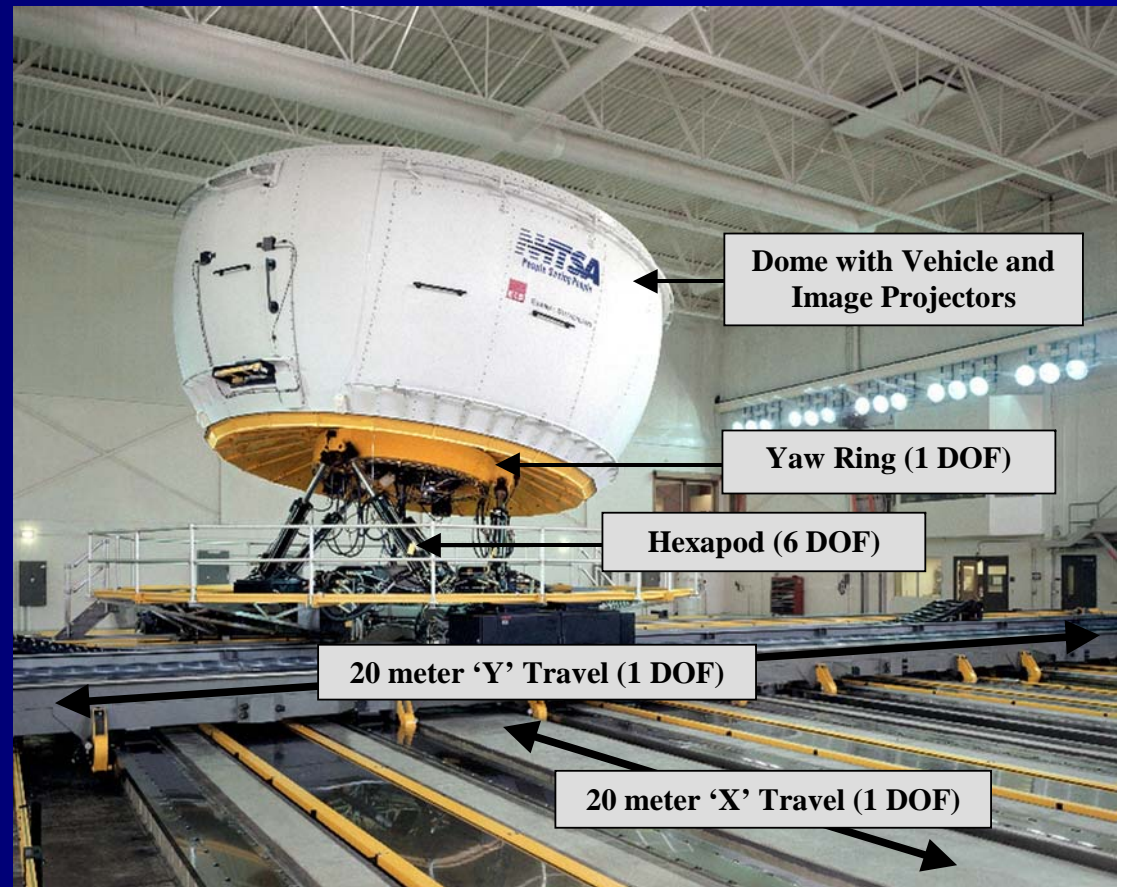
SAE Paper: 2006-01-0559

# Overview

Introduction  
Objectives  
Tire Model  
Tire Properties  
Results  
Conclusions

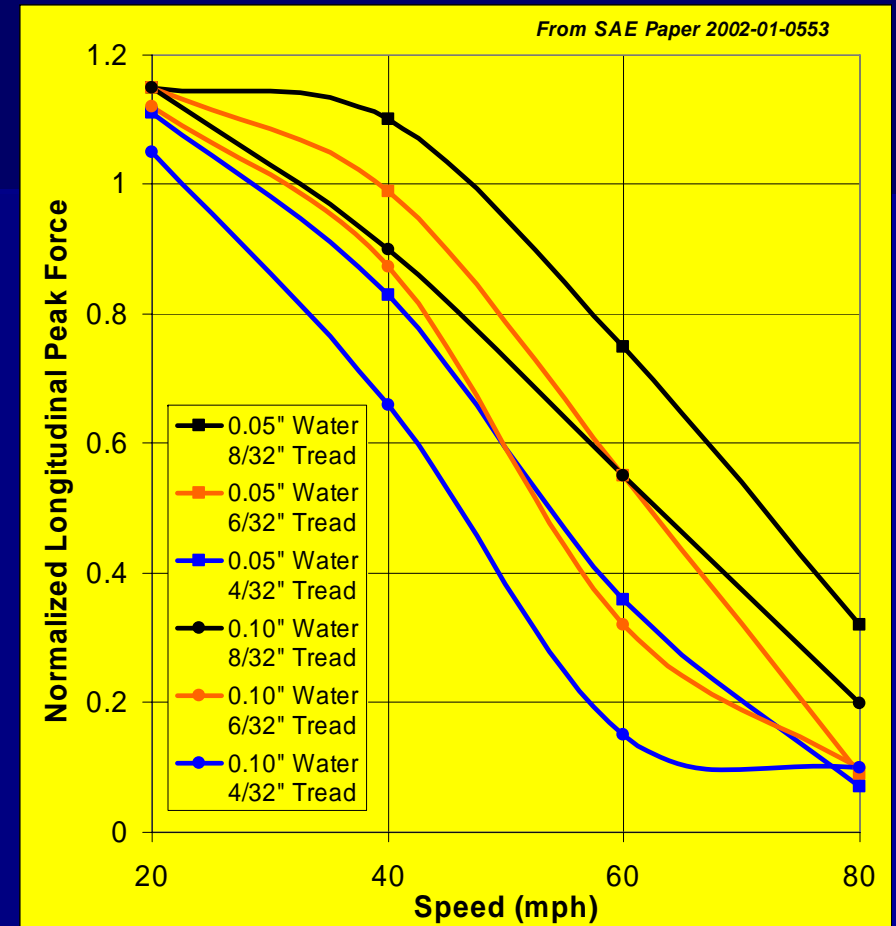
# National Advanced Driving Simulator (NADS)

- 20 m x 20 m X-Y platform
- 330-degree yaw ring
- Hexapod mounted on 6 actuators
- 360-degree field of view
- Four full-size vehicle cabs
- Four actuators at cab "suspensions"
- Driver feels feedback on all controls



# Testing Objectives:

- To develop a tire model for a slippery road to test ESC and other advanced vehicle technology studies
- Peak Coefficient of friction  $< 0.6$  to ensure ESC activation
- Speed dependent model – all other tire properties are fixed
- Testing on laboratory surface (3M surface); variations in roadway micro and macro textures not accounted for
- Selected  $4/32''$  tread depth and  $0.05''$  of water depth, to get a peak about  $0.6$  at  $50$  mph



# Testing Facility and Tires: TIRF at CALSPAN (General Dynamics )

Surface Used: 3M 80-grit-polycat sandpaper

**Goodyear Eagle RSA  
P225/60R16**

All Tires Shaved  
to 4/32" Tread Depth  
All Tire Pressures at 34 psi



# Testing Matrix

## ■ Discrete Cambering At Zero Slip Angle

- Normal loads: 40, 80, 120, 160 and 200% of reference load.
- Wet test speeds: 30, 45, 60 and 75 mph (4 tests) & Dry test speed: 30 mph (1 test)
- Inclination angles: -10, -8, -6, -4, -2, 0, 2, 4, 6, 8 and 10°

## ■ Quasi-Static Steering / Cornering

- Inclination angle: 0°
- Slip angle sweep: 0 to -20 to +20 to 0° at a rate of 3 deg/sec
- Normal loads: 40, 80, 120, 160 and 200% of reference load.
- Wet test speeds: 30, 45, 60 and 75 mph (4 tests)

## ■ Quasi-Static Braking / Driving

- Inclination angle: 0°
- Slip ratio sweep: 0 to -50% to +50% to 0 || Ramp time (0 to 50%) of 1.5 sec
- Normal loads: 40, 80, 120, 160 and 200% of reference load.
- Wet test speeds: 30, 45, 60 and 75 mph (4 tests) & Dry test speed: 30 mph (1 test)

## ■ Quasi-Static Combined Steering / Braking / Driving

- Inclination angle: 0°
- Normal loads: 100% of reference load.
- Steady state slip angles: -6, -4, -2, 0, 2, 4, and 6°
- Slip ratio sweep: 0 to -50% to +50% to 0

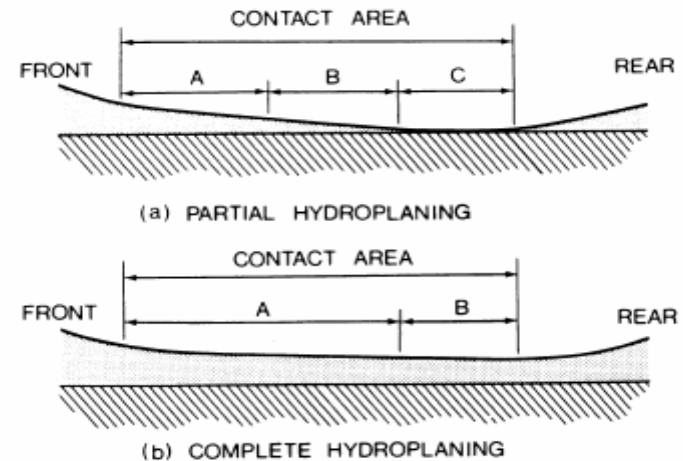
### ■ Ramp time (0 to 50%) of 1.5 sec

- Wet test speeds: 30, 45, 60 and 75 mph (4 tests) & Dry test speed: 30 mph (1 test)

# Tire Wet Contact Phenomena

- At low speed
  - Water affects boundary conditions, lowering friction
  - Difference between dry and wet surface not high
- At higher speed
  - Viscosity induces retardation of water displacement making a wedge of water
  - Difference between dry and wet forces is higher
- At a particular speed, the film covers all the contact surface: Hydroplaning fluids do not sustain shear forces comparable to direct tire contact

Testing Goal



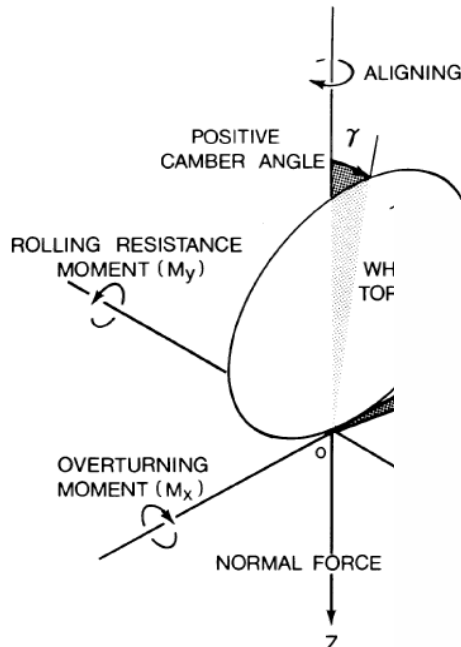
A - UNBROKEN WATER FILM  
B - REGION OF PARTIAL BREAKDOWN OF WATER FILM  
C - CONTACT ZONE

# Tire Model

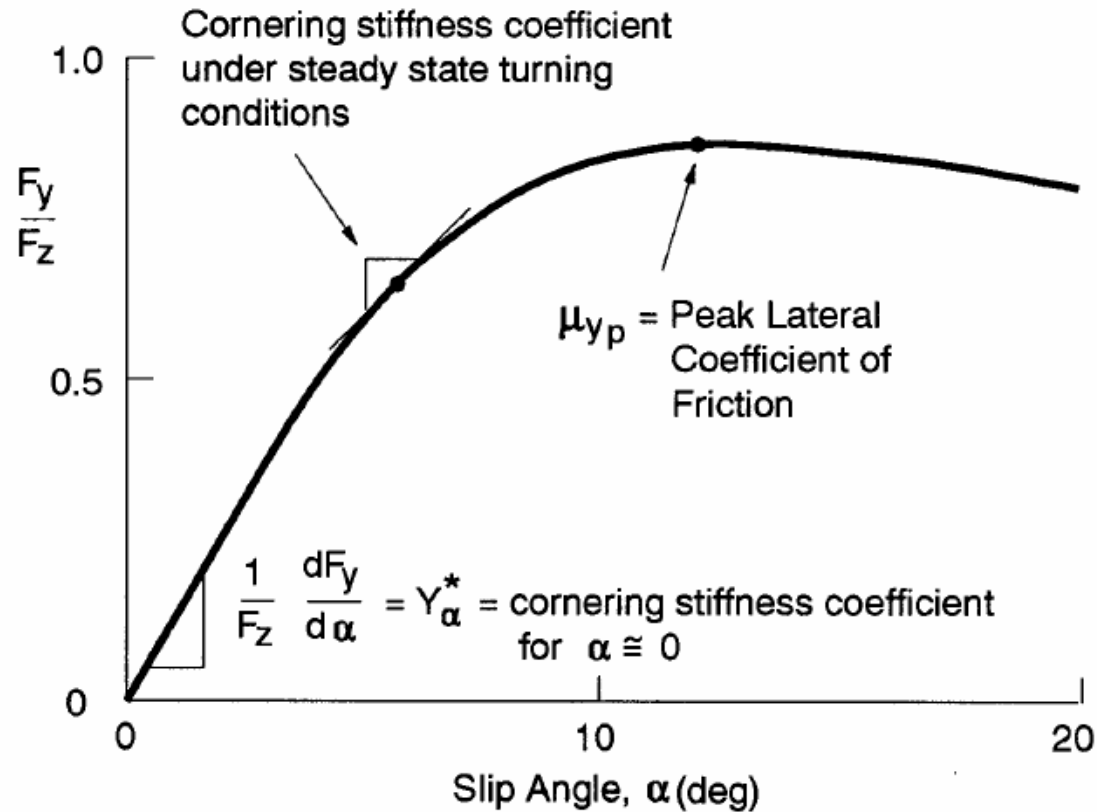
- Semi-empirical based on the brush model
- Friction peak values are fitted to polynomials in function of loads
- Lateral and longitudinal frictions are different
- Stiffnesses are polynomial functions of vertical loads
- Good predictions for combined slips (lateral and longitudinal)
- All parameters are physical parameters
- Linear interpolation between measured data at different speeds is used to model speed dependency



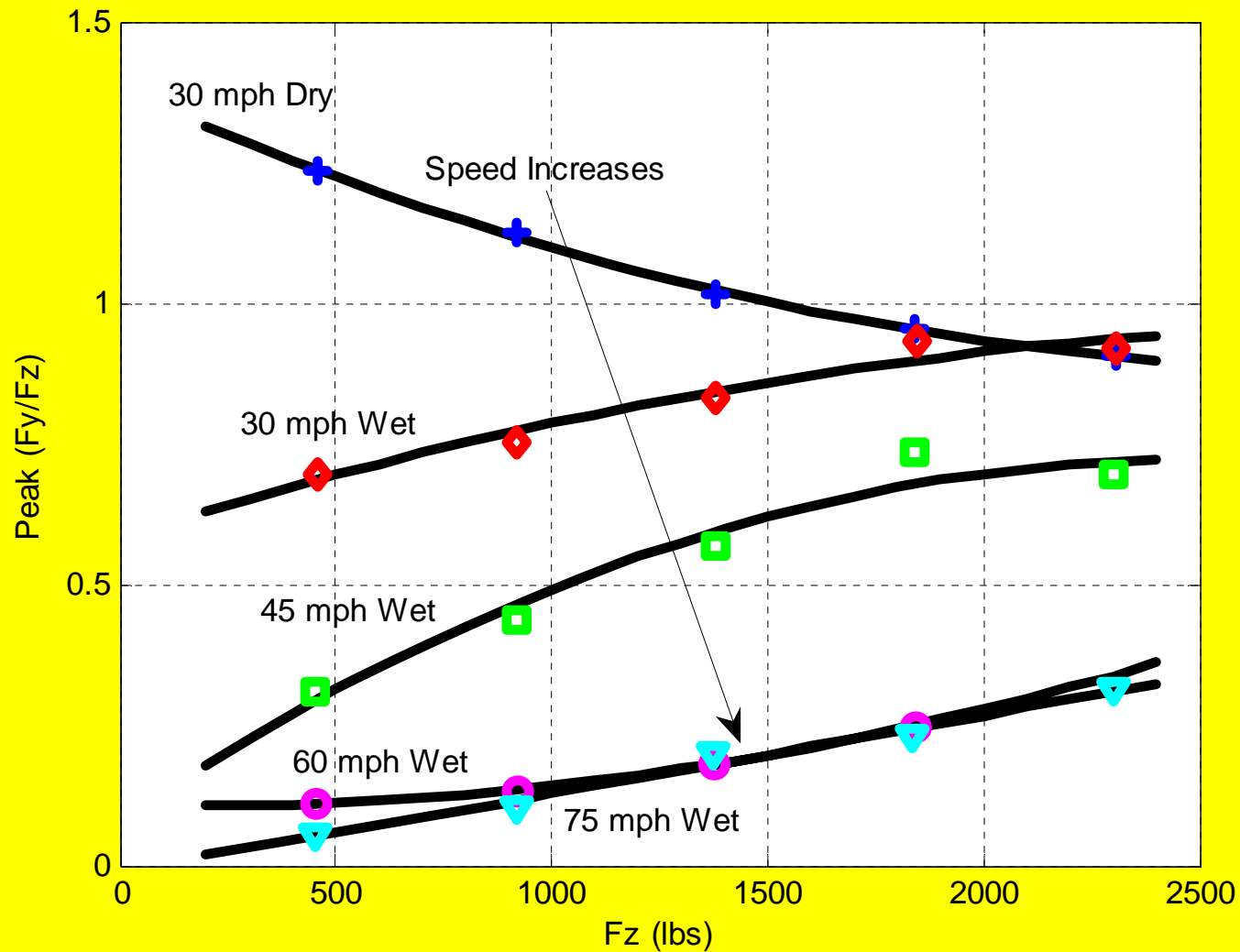
# Tire Fundamental Physical Properties



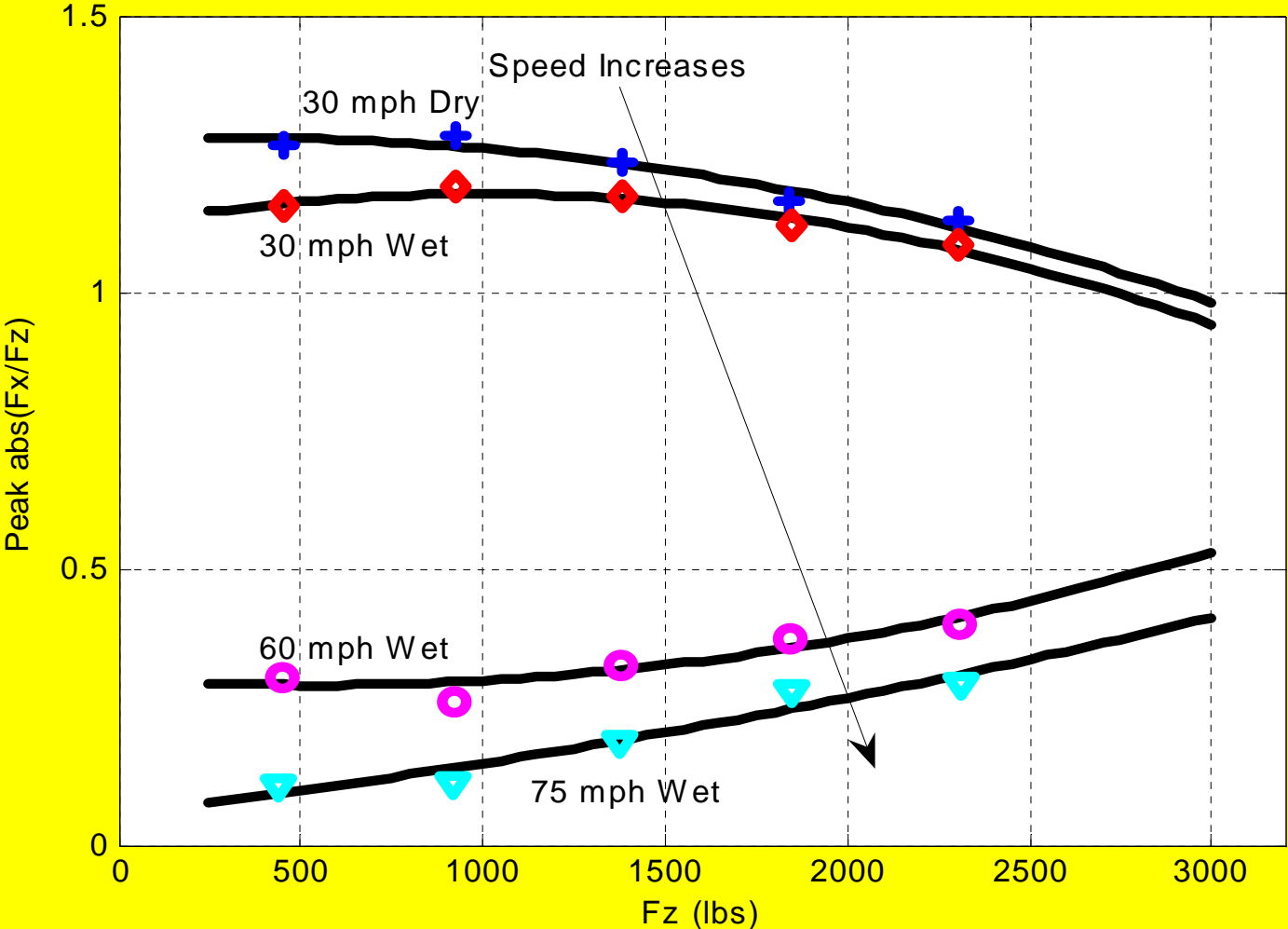
TRACTIVE FORCE ( $F_x$ )  
(DIRECTION OF WHEEL HEADING)



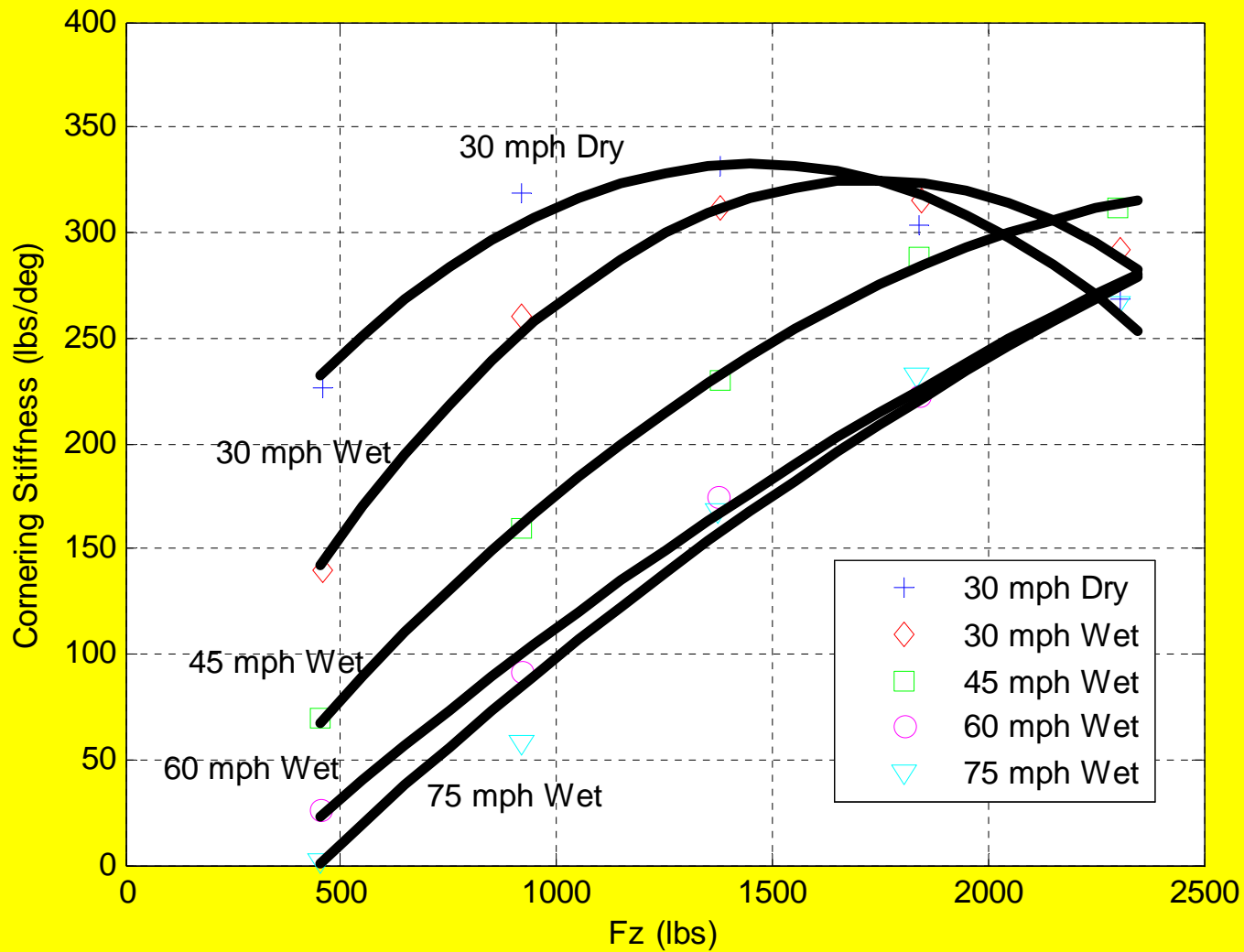
# Lateral Peak Coefficient of Friction



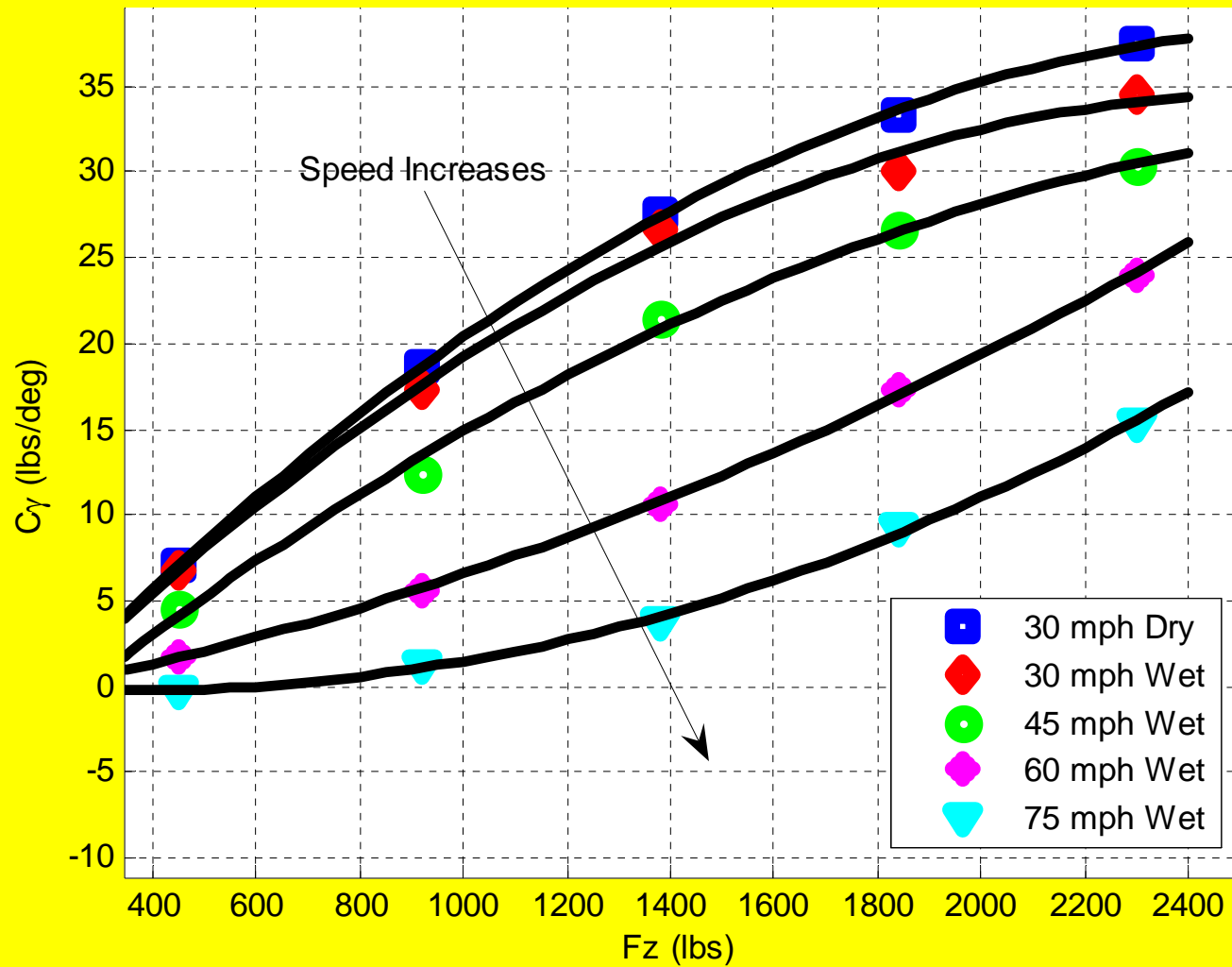
# Longitudinal Peak Coefficient of Friction



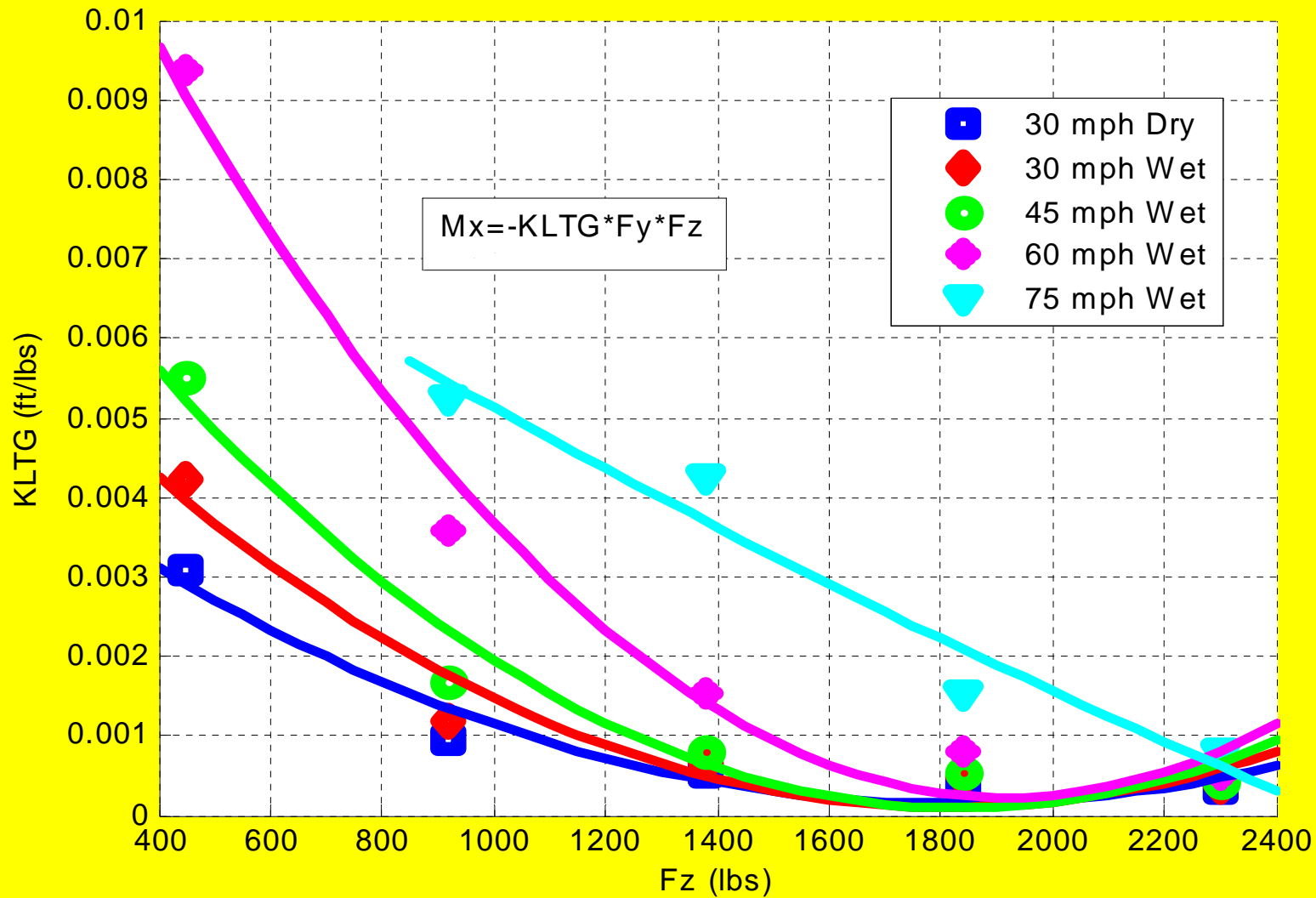
# Effective Lateral Stiffness



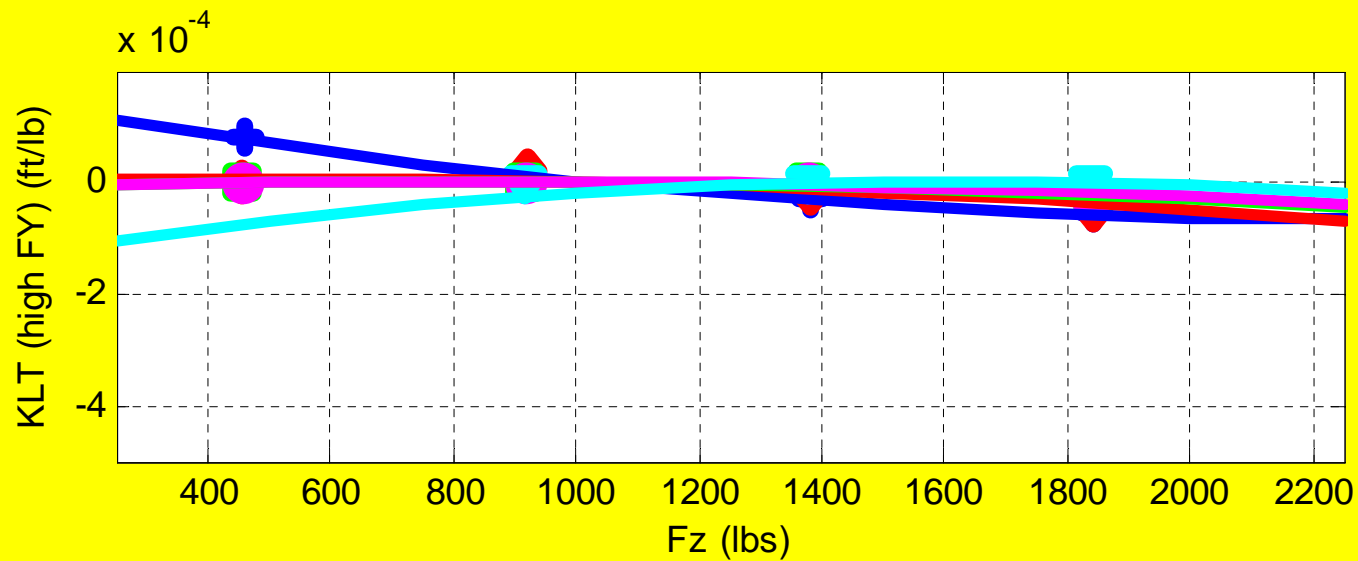
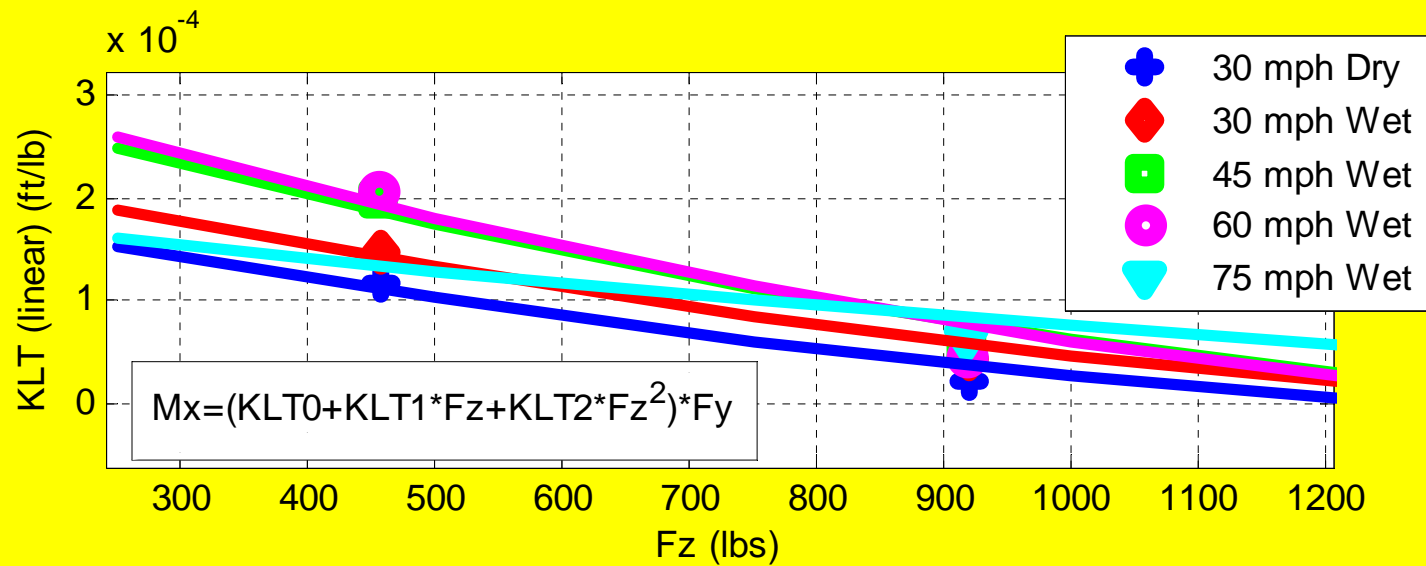
# Inclination Angle Stiffness



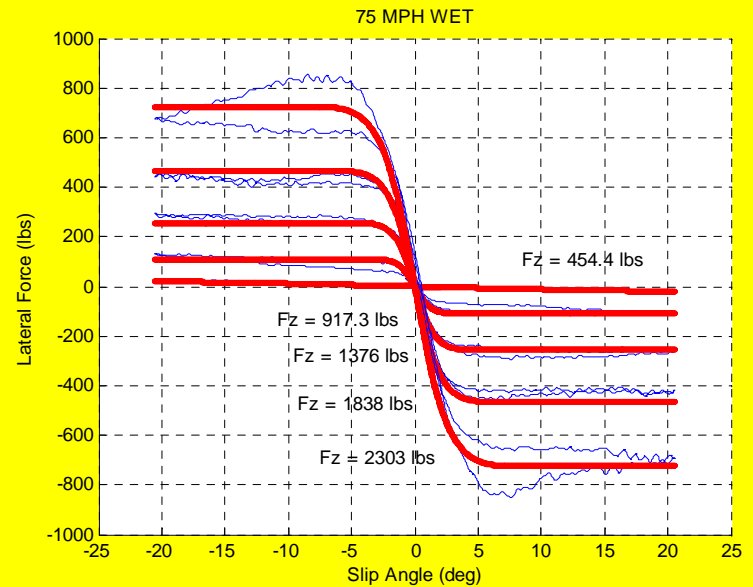
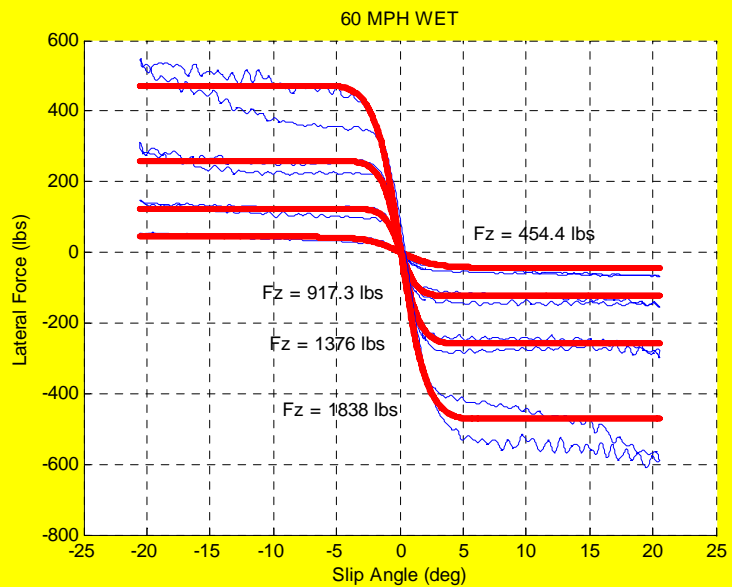
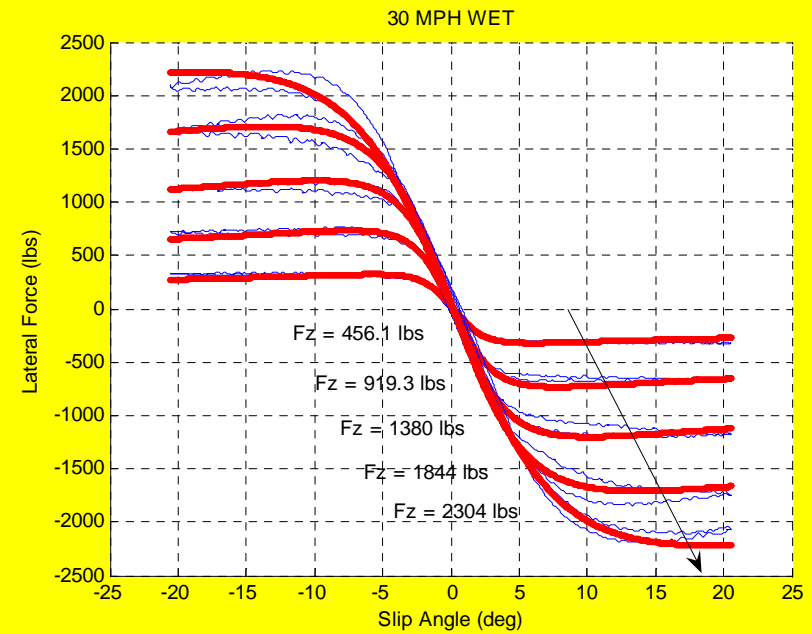
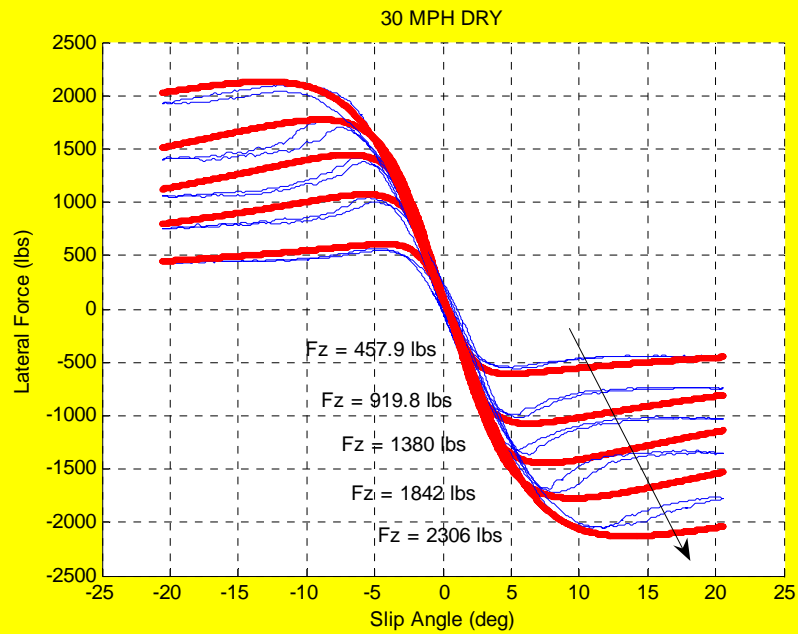
# Overturning Moment Inclination Angle Stiffness



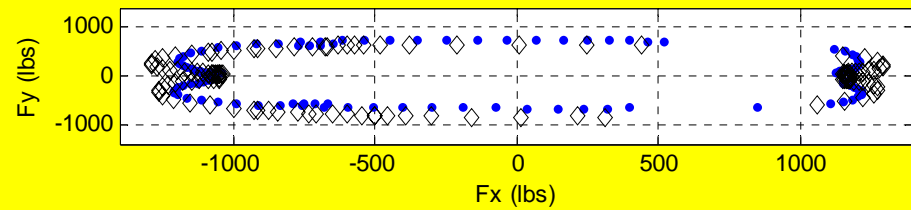
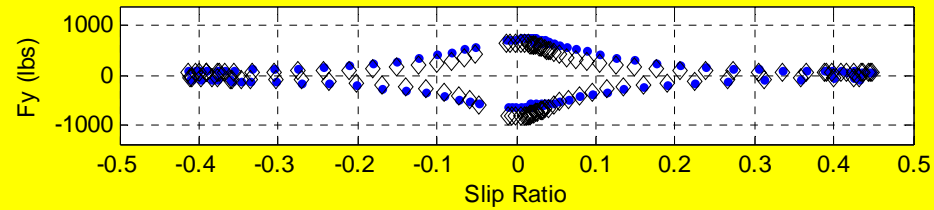
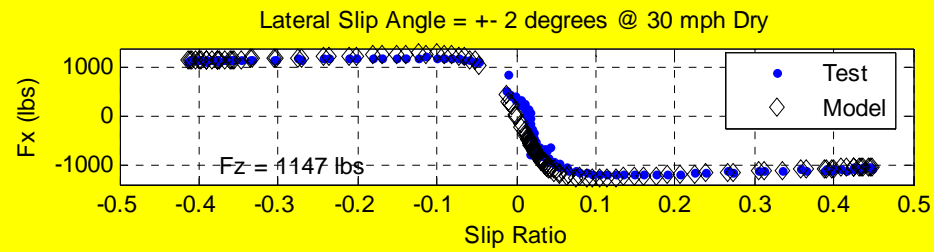
# Overturning Moment Stiffness



# Results (Fy)

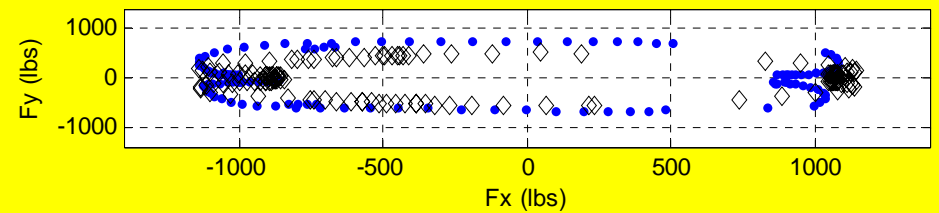
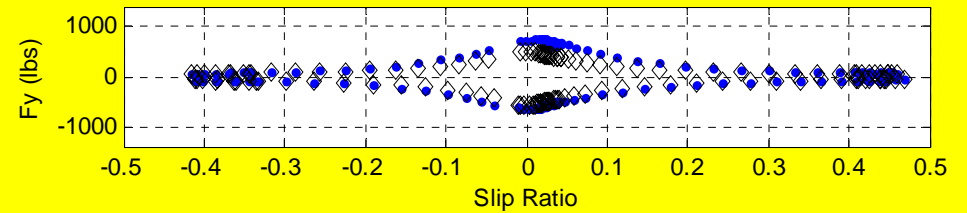
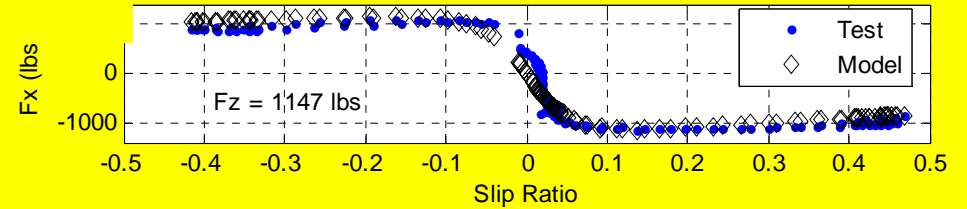


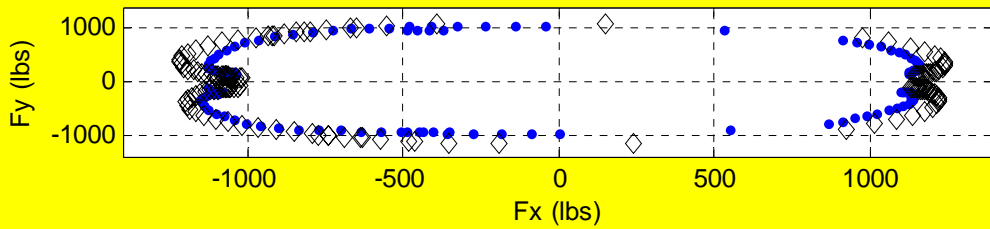
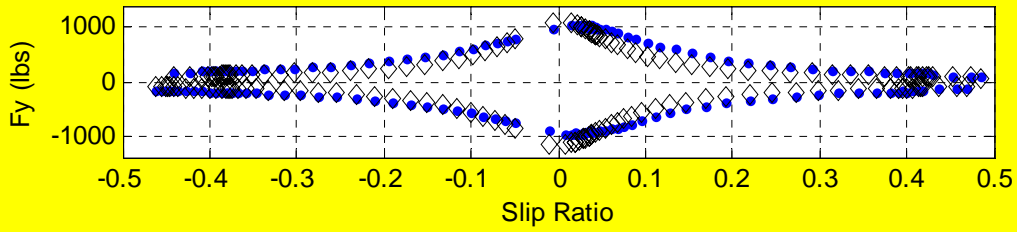
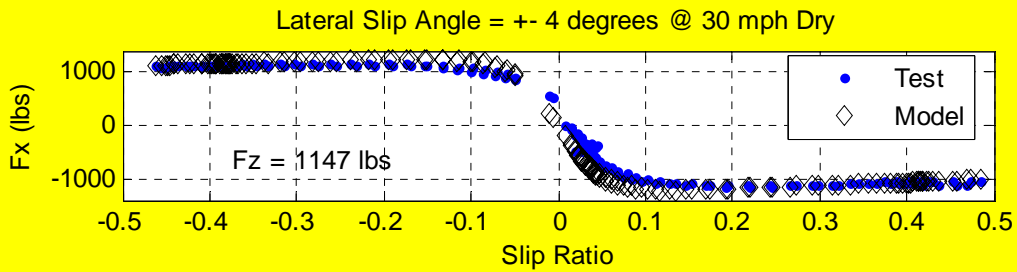




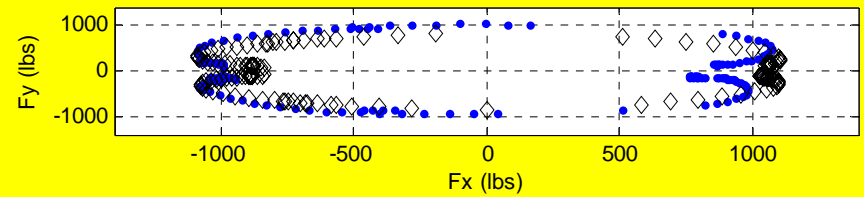
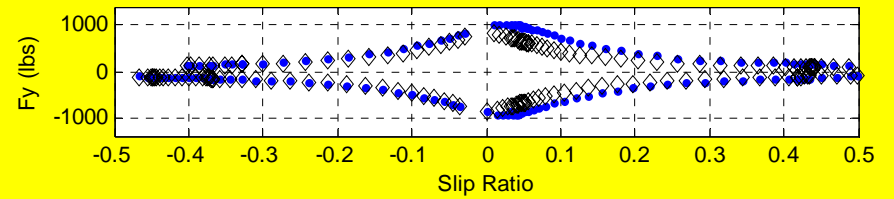
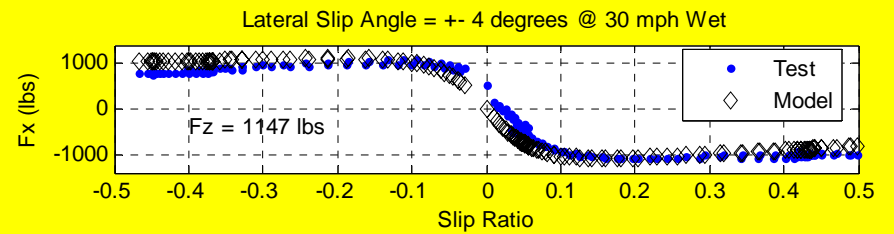
# Combined

Lateral Slip Angle = +/- 2 degrees @ 30 mph Wet

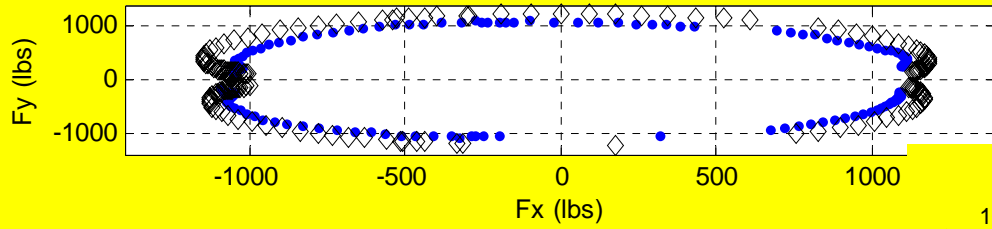
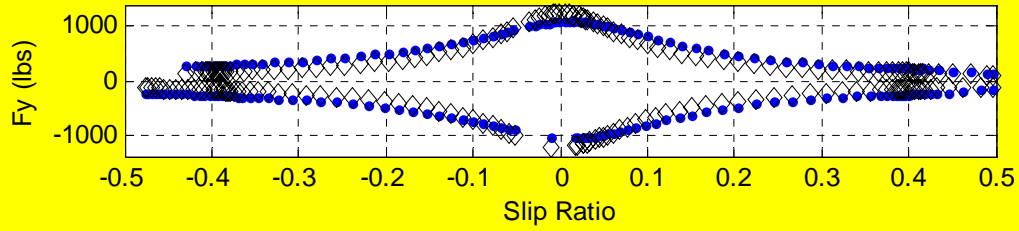
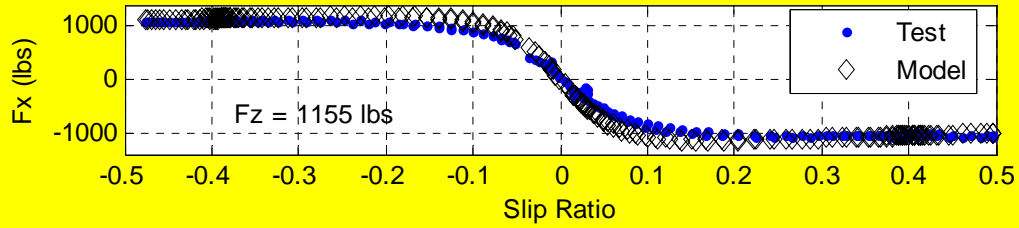




# Combined

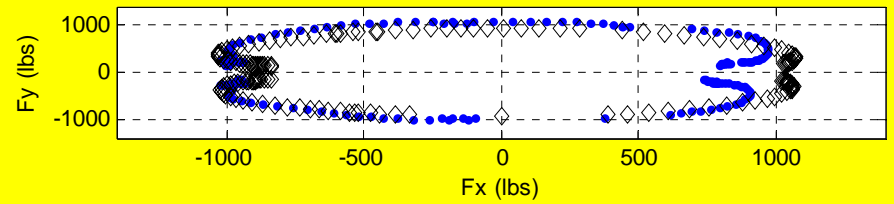
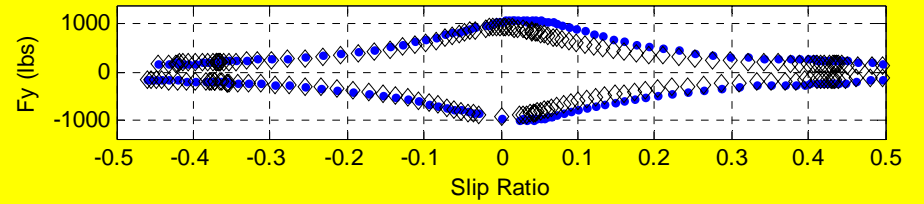
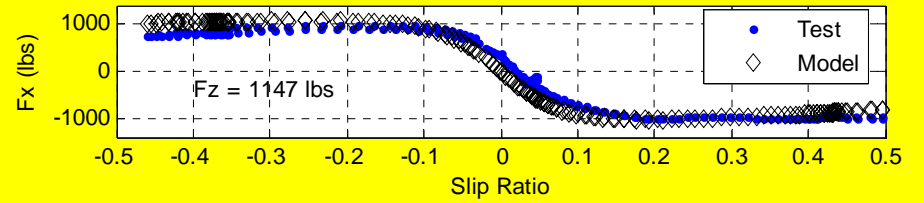


Lateral Slip Angle = +- 6 degrees @ 30 mph Dry



# Combined

Lateral Slip Angle = +- 6 degrees @ 30 mph Wet



# Important Differences with On-the-Road Tires/Surfaces

- Tires were shaved, aging effects is ignored (tire properties change with age and environment)
- NHTSA studies indicated the average tread depth for in-service tires is about 7/32", yet we used 4/32" to meet peak coefficient of friction target value
- Variations of tread depth, water depth, tire pressure, tire construction, surface texture, and tread patterns are not addressed
- Speed is the only variable affecting the model
- The results from the model is physically sound – compares well with experimental results and can be used to validate ESC systems

# Conclusions

- Longitudinal and lateral force and moment data were collected
- Test conditions were created such that a high coefficient of friction was generated at low speeds and a lower coefficient was generated at high speeds

# Conclusions (cont.)

- Tire parameters were calculated from the test data
- Parameters were verified by comparing calculated forces to measured forces

# Questions ?

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